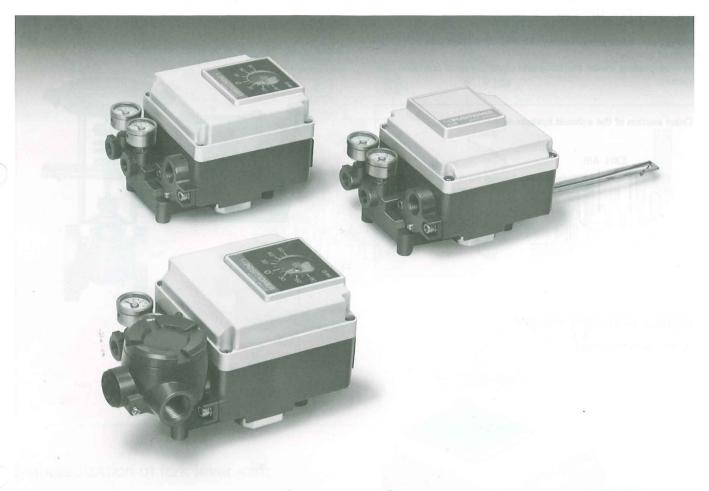


# Electro-Pneumatic Positioner Series IP6000/IP6100



High performance positioner
Resistant to hostile environments.
Exceptional shock and vibration performance.

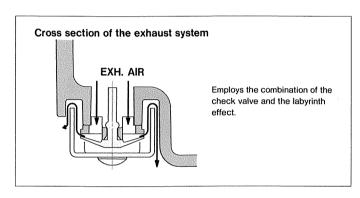
# Series IP6000/IP6100

No resonances: 5~200Hz

# Approved by JIS F8007 IP55

A centralized exhaust system enhances both dust-proof and water-proof qualities.

Epoxy-type coating inside the body and cover prevents corrosion due to moisture.

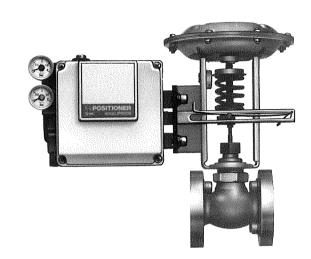


# Easy to attach small diaphragm actuators

The pneumatic and electrical ports are on the side of the body and do not interfere with the feedback lever on the other side.

# Stable operation

Control is very stable even on small sized actuators.



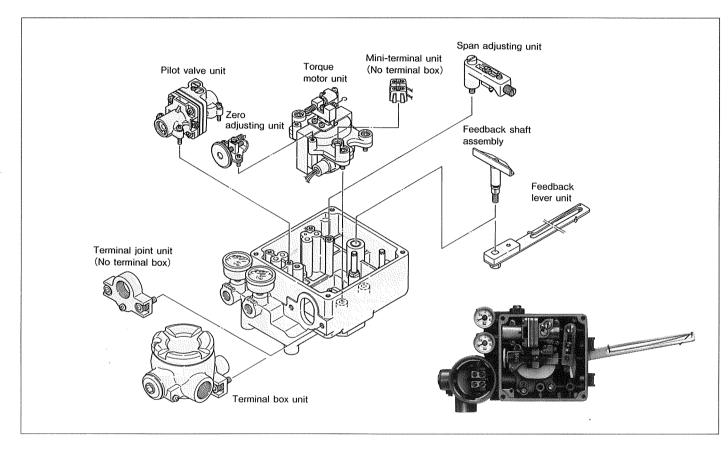
# Compact and light weight

20% Lighter than other types.



# Easy maintenance

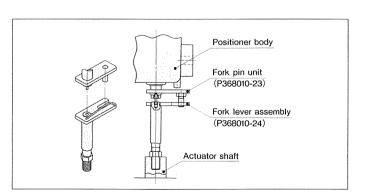
Maintenance and parts replacement made easy by modular construction.



# Standardization of fork lever joint

(IP6100 type)

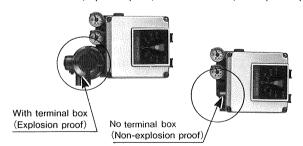
Linkage design tolerates a slight misalignment of shafts



Position indicator: Standard equipment (IP6100 type)

# Two electric wiring configurations

With terminal box (Explosion proof) •No terminal box (Non-explosion proof)



Span adjuster accommodates ½ split range.

# Excellent explosion proof specification

Explosion proof standard—sd2G4/ExsdIIBT5

# Interchangeable

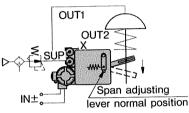
Compatible with IP600 series mounting bracket.

# Piping method

# IP6000 Lever type

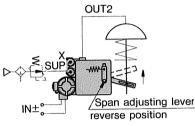
# Single action

Positive operation: When the input signal is increased, the stem extends.



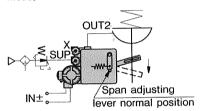
OUT2 is Plugged

Reverse operation: When the input signal is increased, the stem retracts. (Reverse valve operation by its positive operation mode)



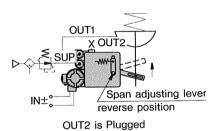
**OUT1** is Plugged

When the input signal is increased, the stem extends. (Positive valve operation by its reverse operation mode)



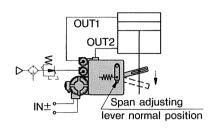
OUT1 is Plugged

When the input signal is increased, the stem retracts.

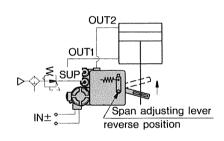


# **Double action**

Positive operation: When the input signal is increased, the cylinder rod extends.



Reverse operation: When the input signal is increased, the cylinder rod retracts.

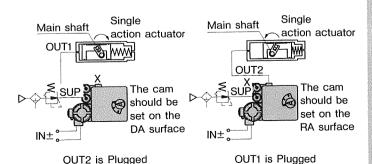


# IP6100 Rotary type

# Single action

Positive operation: When the input signal is increased, the actuator shaft rotates in a counter clockwise direction.

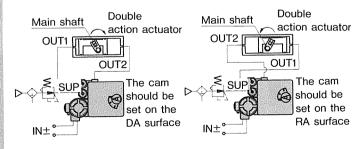
Reverse operation: When the input signal is increased, the actuator shaft rotates in a counter clockwise direction.



### **Double action**

Positive operation: When the input signal is increased, the actuator shaft rotates in a clockwise direction.

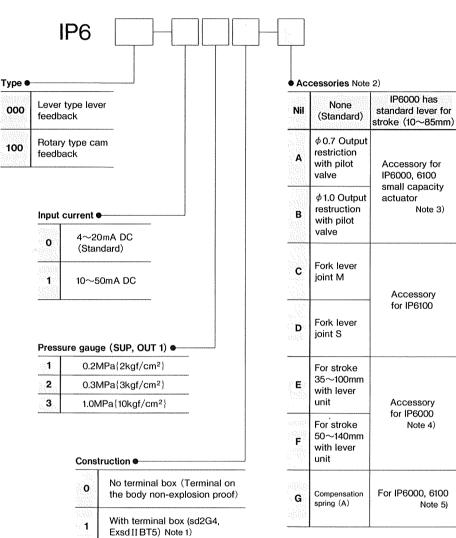
Reverse operation: When the input signal is increased, the actuator shaft rotates in a counter-clockwise direction.





# IPSIOO

# How To Order



Note 1) For construction No. 1 (with terminal box), the ambient and fluid temperatures are as follows:

- Non-explosion proof (non hazardous locations only) —— -20~80°C
- Two labels (sd2G4, Exsd II BT5) are on the body.
- Note 2) If two or more accessories are required, the part numbers should be made according to alphabetical order. (ex. IP6000-011-AG)
- Note 3) "A" is applied to approx 90cm3-capacity actuator.
  - "B" is applied to approx 180cm3-capacity actuator.
- Note 4) Standard lever is not attached.
- Note 5) The following combinations are available: A + G or B + G

Specifications

Туре	IP6000 Lever type lever feedback		IP6100  Rotary type cam feedback	
1,400				
Item	Single action	Double action	Single action	Double action
Input current	4~20mADC(Standard) Note 1)			
Coil resistance	235±15Ω (4~20mADC)			
Supply air pressure	0.14~0.7MPa{1.4~7.1kgf/cm²}			
Stroke	10~85mm (Deflect	ction angle $10^{\circ} \sim 30^{\circ}$ ) $60^{\circ} \sim 100^{\circ}$ Note 2)		OO® Note 2)
Sensitivity	Within 0.1%F.S.	Within 0.5%F.S.		
Linearity	Within ±1%F.S.	Within ±2%F.S.		
Hysteresis	Within 0.75%F.S.	Within 1%F.S.		
Repeatability	Within ±0.5%F.S.			
Coefficient of temperature	Within 0.1%F.S./°C			
Output flow	Note 3) 80 ℓ/min (ANR) or more (SUP=0.14MPa)			
Air consumption (Bleed)	Note 3) 5 ℓ/min(ANR) or less (SUP=0.14MPa)			
	−20°C~80°C (Non-explosion proof)			
Ambient and fluid temperature	−20°C~70°C (Pressure tight explosion proof sd2G4)			
	-20°C∼60°C(Pressure tight explosion proof Exsd II BT5)			
Explotion proof	Pressure tight			
construction	explosion proof construction	Exsd II BT5 (Type certification approval number. No.C10474)		
Air port	Rc(PT)1/4 female			
Electrical connection	G(PF) ½ female			
	Conduit system Pressure tight packing system			
Wiring method	Resin G(PF) ½ connector (Non-Explosion proof, option)			
Material	Aluminum diecast body			
Weight	With terminal box 2.6kg (None 2.4kg)			

Note 1)  $\frac{1}{2}$  Sprit range (Standard) Note 2) Stroke adjustment:  $0\sim60$ ,  $0\sim100^\circ$ 

Note 3) Standard air temperature: 20° (298k), Absolute pressure: 760mmHg, Relative humidity: 65%

# Fork lever joints (IP6100 type)

Fork-lever rotary joints are available that tolerate small misalignments between positioner and actuator shaft.

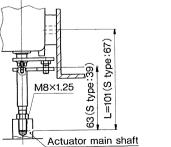
These are available in two standard sizes.

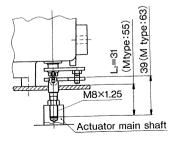
# Fork lever joint

Part name	Part number
Fork lever assembly M	P368010-24
Fork lever assembly S	P368010-25

Side mounting with the fork lever assembly M

Rear mounting with the fork lever assembly S



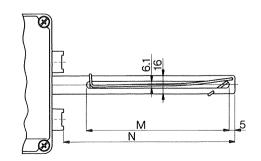


# External feedback lever (IP6000 type)

The feedback lever is selected according to valve stroke. Consult factory for strokes less than 10mm.

## External feedback lever

Stroke	Order code	Unit number	Size M	Size N
10~85mm	(Nil)	P368010-20	125	150
35~100mm	(E)	P368010-21	110	195
50~140mm	(F)	P368010-22	110	275



# Pilot valve with output restriction (IP6000, 6100 type)

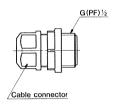
In general, mounting on a small-size actuator may cause hunting. For prevention, a pilot valve with a built-in output restriction is available. The restriction is removable.

### Restrictions

Actuator Capacity	Orifice size	Part number	Pilot unit part number
90cm <sup>3</sup>	φ0.7	P36801080	P368010-28
120cm <sup>3</sup>	φ1.0	P36801081	P368010-29

# Resin connector (Non-explosion proof specification)

Optional cable connectors are available for two different cable sizes. These are not for explosion proof applications.



### Cable connector (Option)

Part name	Part number	Suited cable outer diameter
Resin-made cable clamp unit (A)	P368010-26	<i>φ</i> 7~ <i>φ</i> 9
Resin-made cable clamp unit (B)	P368010-27	φ9~ φ11

# Installation

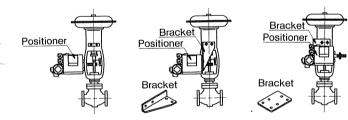
# IP6000 type (Lever type lever feedback)

The unit should be mounted using bolts firmly fixed through mounting holes on the side or back of the positioner.

No bracket

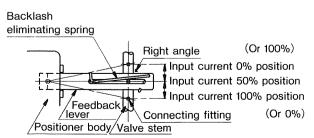
L-type bracket

Front bracket



A connecting fitting or pin to transfer the displacement of valve stem should be mounted at a position so that the feedback lever is at right angles to the valve stem for an input current of 50%. The following figure is the configuration viewed from the front.

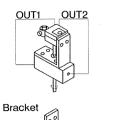
# Installing feedback lever



A fullscale deflection of 20° is optimum. It should be at least 10° and at most 30° to achieve specified accuracy and linearity.

# IP6100 type (Rotary type cam feedback)

The positioner should be mounted so that the feedback shaft is aligned with the shaft of the rotary actuator.







# **Explosion Proof**

This product has the following approvals.

\*\*sd2G4:Explosion-protected construction standard of electrical equipment (Notification No.16 of the ministry of labor, Japan in 1969.)

※Exsd II BT5: Newly established standard based on international specifications (IEC No.79).

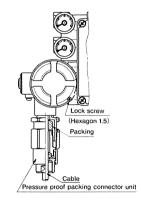
Use as sd2G4

- (A) Pressure-proof packing. As shown below in the chart, use "cable gland" (option).
- (B) Flameproof threaded joint steel conduit type lead in method.

Use as Exsd II BT5

- (A) Pressure-proof packing.
  As shown below in the chart, use "Cable gland"(option).
- (B) Metal Piping. Attach the sealant fitting near the cable port.

For details, refer to "Factory electric equipment explosion proof guide line" published by the industry safety association.



Cable gland armour with pressure proof packing (Option)

Part name	Part number	Suited cable outer diameter
Pressure proof packing connector unit	P368010-32	φ7.0~ φ10.0
	P368010-33	φ10.0~φ12.0

# **Precautions**

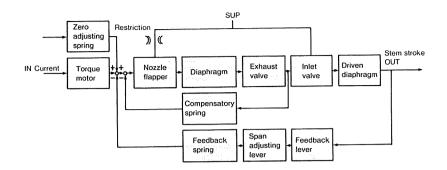
- Avoid impact to positioner while transporting and handing.
- Operate within specified temperature range to prevent deterioration of seals.
- 3 Do not remove terminal cover in a hazardous location.
- Oovers for the terminal and body should be in place while operating in the presence of moisture and gases.
- To extend the life of the positioner when used outdoors, extra protection is recommended against rain and dust. Units should also be protected against moisture in high heat and humidty conditions during transport, packaging should protect against moisture.

# Principle of Operation

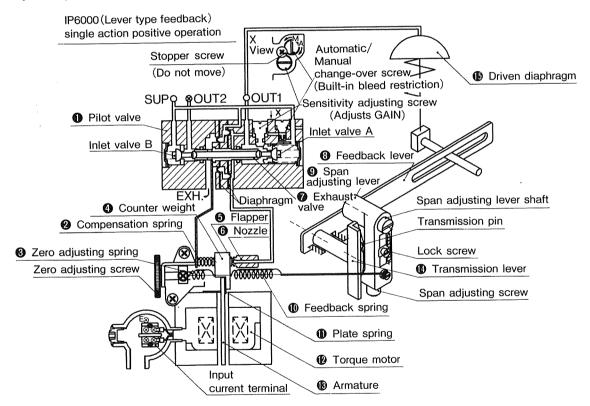
# IP6000 type

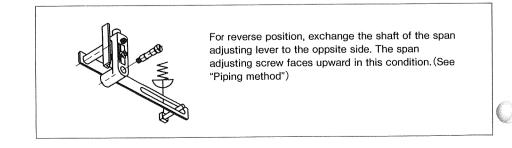
When the input current increases, 10 the plate spring of **1** the torque motor will work as a pivot, (B) armature will receive a counter clockwise torque, 4 the counter weight will be pushed to the left, the clearance between 6 the nozzle and 5 the flapper will increase, and the nozzle back pressure will decrease. Consequently, 7 the exhaust valve of 10 the pilot valve moves to the right, the output pressure of OUT 1 increases and (6) the diaphragm moves downwards. The motion of the diaphragm acts on the feedback spring through (3) the feedback lever, (6) the transmission lever and 9 the span adjustment lever to rest at the balance position generated by the input current. 2 The compensation spring is for direct feedback of the motion of 7 the exhaust valve to 4 the counter weight to increase the stability of the loop. The zero point should be adjusted by change of 3 the zero adjustment spring tention.

# IP6000 type Block diagram of operating principle



## IP6000 Principle of operation

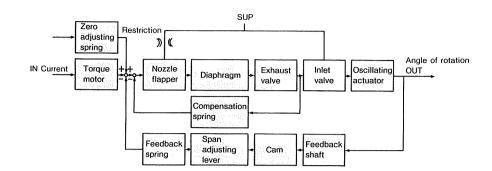




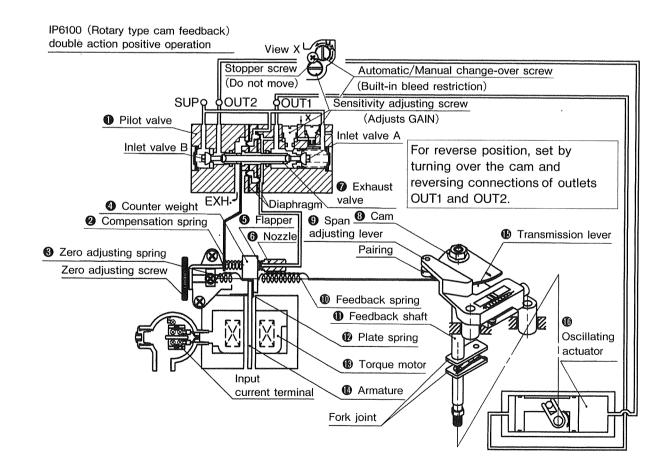
# IP6100 type

When the input current increases, @ the plate spring of (8) the torque motor will work as a pivot, (1) armature will receive a counter-clockwise torque, 4 the counter weight will be pushed to the left and the clearance between 6 the nozzle and 6 the flapper will increase, and the nozzle back pressure will decrease. Consequently, 7 the exhaust valve of 10 the pilot valve moves to the right, the output pressure of OUT 1 increases, that of OUT 2 decreases and (6) the rotary actuator moves. The motion of ® the actuator acts on @ the feedback spring through 10 the feedback shaft, 13 the cam, 9 the span adjustment lever and 19 transmission lever to rest at the balance position generated by the input current. 2 The compensation spring is for direct feedback of the motion of 7 the exhaust valve to 4 the counter weight to increase the stability of the loop. The zero point should be adjusted by change of 8 the zero adjustment spring tension.

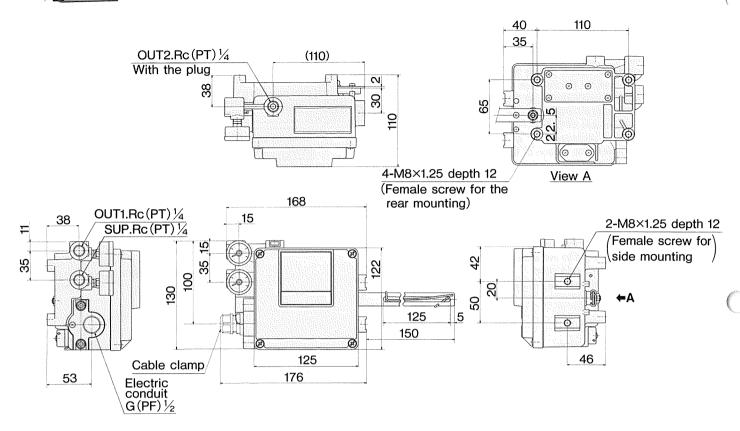
# IP6100 type Block diagram of operating principle



# IP6100 Principle of operation

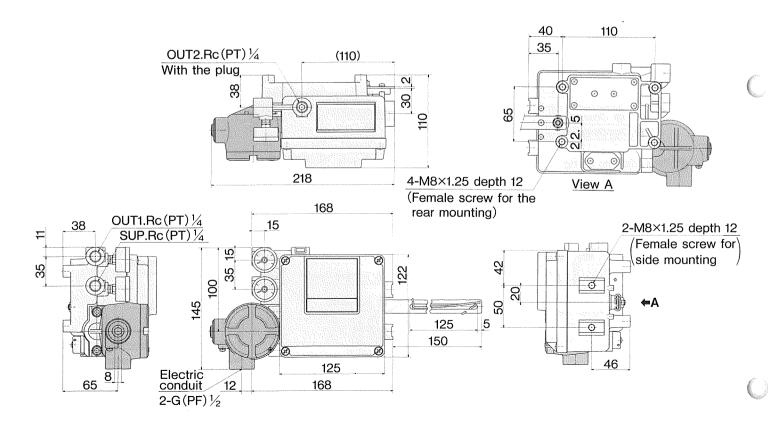






IP6000 type(Lever type feedback(With terminal box))

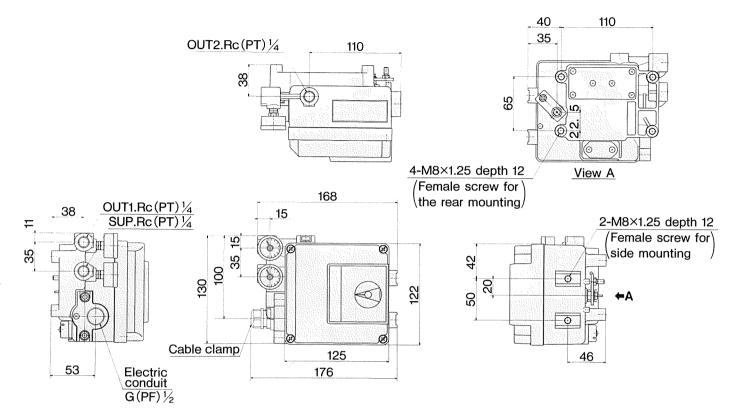
Scale: 1/5



Scale: 1/5









IP6100 type(Rotary type cam feedback(With terminal box))

Scale: 1/5

